

# CISC 3250

## Systems Neuroscience

### Perception



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JMH 332

### Pathways to perception in 3 (or fewer) synaptic steps

0 Input through sensory organ/tissue

1 Synapse onto neurons in spinal cord/brain stem

2 Synapse onto neurons in thalamus

3 Synapse onto cortical neurons in “primary \_\_\_\_ cortex”

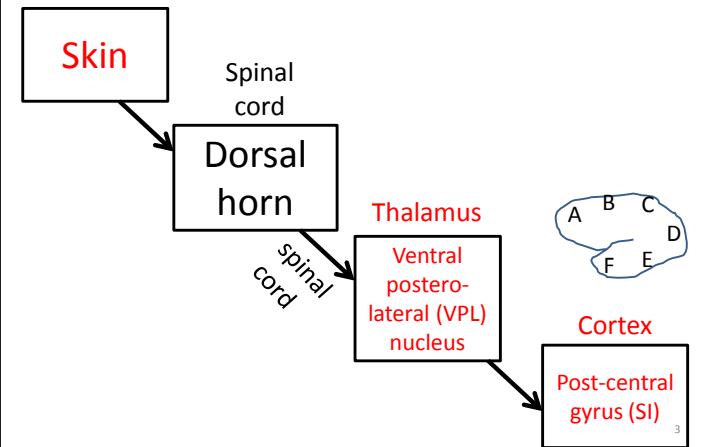
4<sup>+</sup> Further cortical processing

- Types of percepts in this lecture:
- Tactile (touch)
  - Audition (sound)
  - Vision (sight)



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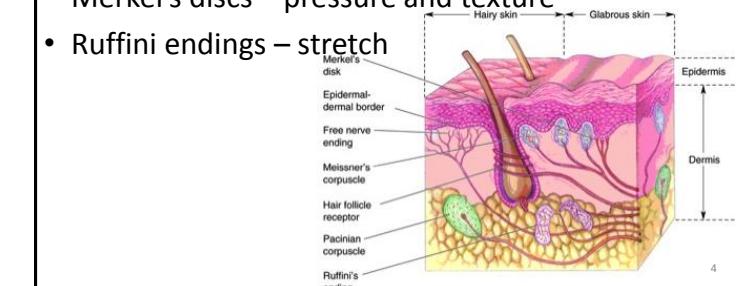
### Touch/“Tactile”



### Touch: Inputs

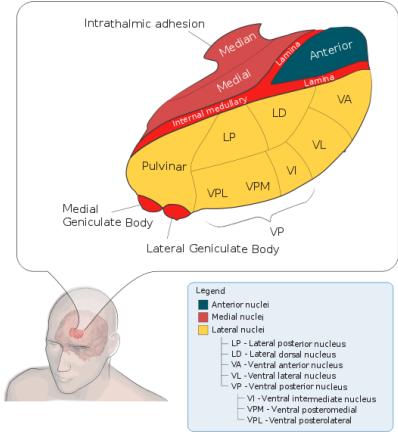
#### Mechanoreceptors in skin

- Pacinian corpuscles – vibrations
- Meissner's corpuscles – light touch
- Merkel's discs – pressure and texture
- Ruffini endings – stretch



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## Thalamus – the “relay” station



Region names largely based on location

VPL for somatosensation

VPL =  
Ventral (bottom)  
Posterior (back)  
Lateral (side) Nucleus

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## Hearing/“Auditory”

### Cochlea

Cochlear nerve

Cochlear nucleus (-> Superior olive) -> Inferior colliculus

Brain stem

Recall: in cochlea have tonotopy  
Neurons selective for specific frequencies

Geniculate nuclei at most posterior ventral spots in thalamus

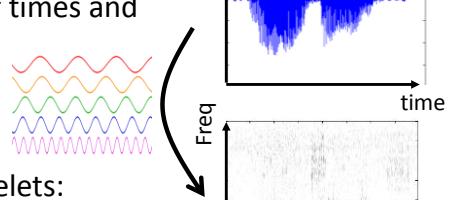
### Thalamus

Medial geniculate nucleus (MGN)

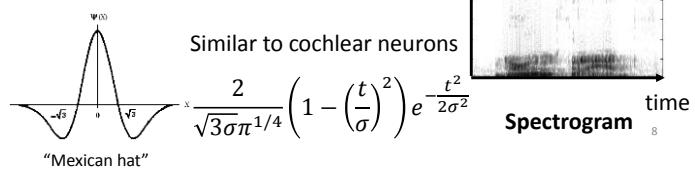
Cortex  
Primary auditory cortex (AI)

## Hearing and frequency decomposition

Sound consists of times and frequencies

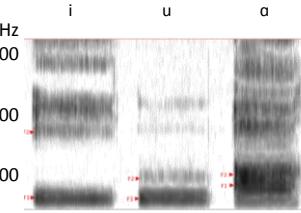


Time-bound wavelets:

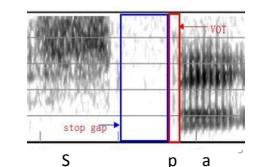


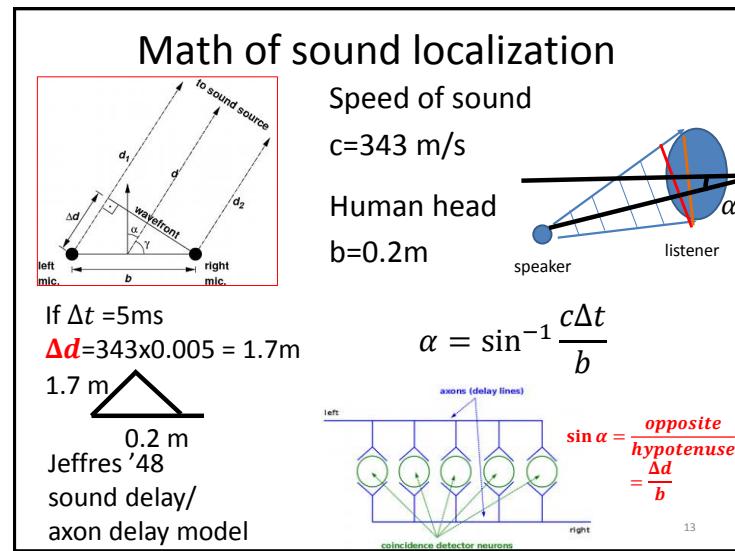
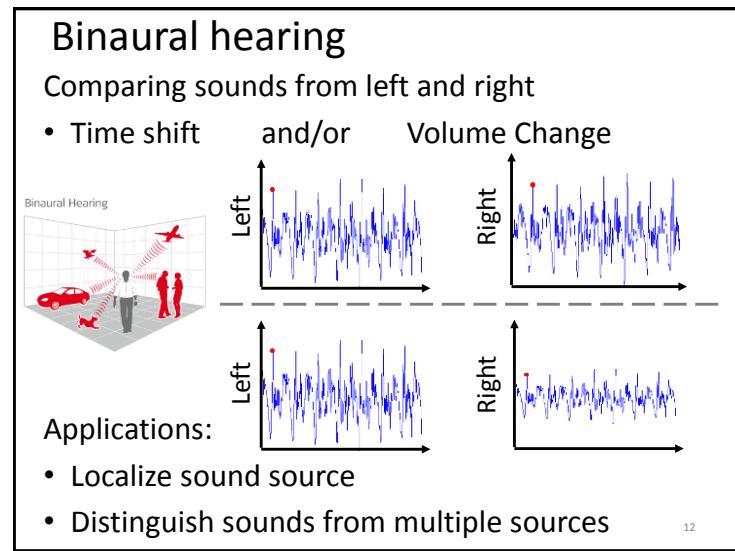
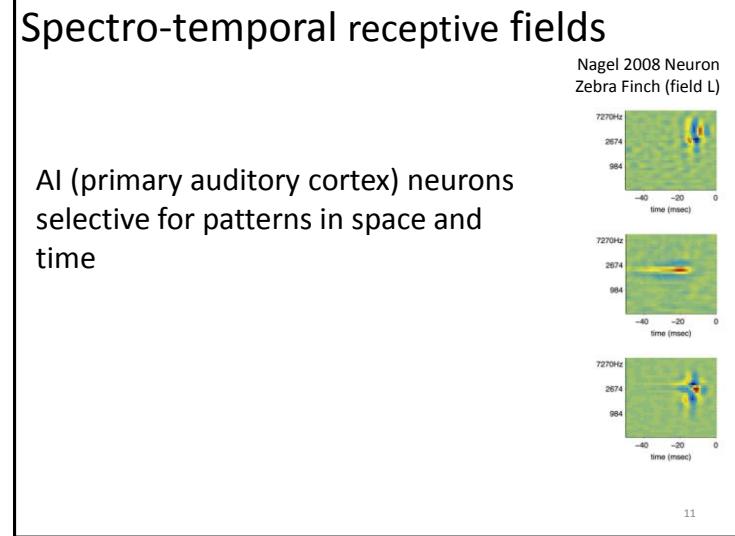
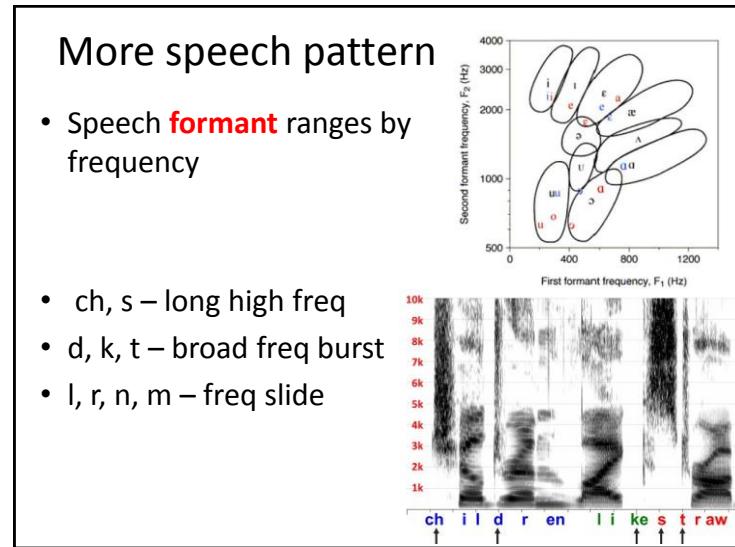
## Common patterns in speech

- Vowels (a,e,i,o,u) correspond to steady frequency combinations



- Consonants may be broad-range frequencies, or sweeps





## Math of sound localization

Speed of sound  
c=343 m/s

Human head  
b=0.2m

If  $\Delta t = 0.5\text{ms}$   
 $\Delta d = 343 \times 0.0005 = 0.17\text{m}$

$$\alpha = \sin^{-1} \frac{c\Delta t}{b}$$

$$\sin \alpha = \frac{0.17}{0.2} = 0.85$$

$$90^\circ = 1.57 \text{ rad } (\frac{\pi}{2} \text{ rad})$$

$$\alpha = \sin^{-1} 0.85 \times \text{radians:}$$

$$\alpha = 58^\circ$$

$$\frac{90x}{1.57} \approx \frac{360x}{2\pi} \text{ degrees}$$

Sound gets R ear @ 1345.2 ms  
to L ear @ 1345.7 ms

## Math of sound localization

Speed of sound  
c=343 m/s

Human head  
b=0.2m

$$\alpha = \sin^{-1} \frac{c\Delta t}{b}$$

Pick direction for comparison

$$\Delta t = \begin{cases} > 0 & \text{rightSound earlier} \\ < 0 & \text{leftSound earlier} \end{cases}$$

## Math of sound localization

Speed of sound  
c=343 m/s

Human head  
b=0.2m

$$\alpha = \sin^{-1} \frac{c\Delta t}{b}$$

x radians:  
 $\frac{90x}{1.57} \approx \frac{360x}{2\pi} \text{ degrees}$

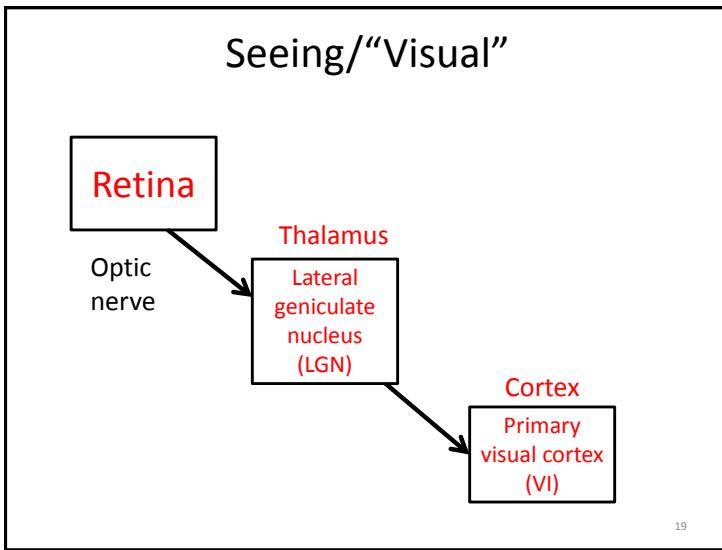
Sound gets R ear @ 258.5 ms 285.5ms  
Get to L ear @ 285.3 ms

Which ear is sound closest to?  
The ear that sound arrives at first  
Ear with smaller time of arrival

$$\Delta d = c\Delta t = 343 \times (0.2855 - 0.2853)$$

$$\sin \alpha = \frac{\Delta d}{b} = \frac{343 \times 0.0002}{0.2} = \frac{.0686}{0.2} = 0.35$$

What's my  $\alpha$ ?  
Closer to L ear

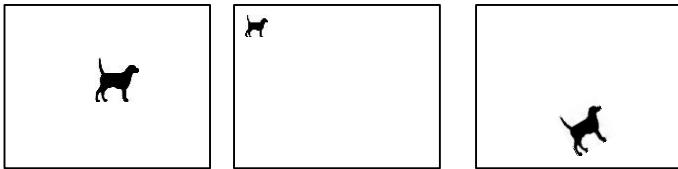
$$\alpha = \text{asin}(0.35) = 20^\circ$$


## Sensitivity to perceptual variations

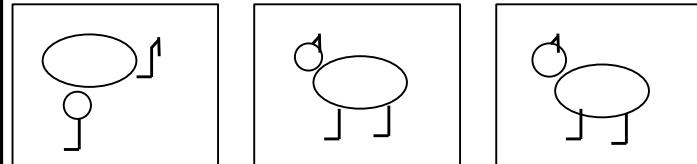
- V1: Surround-suppression for shifted edges



- PFC: Same object detected at diverse locations and scales



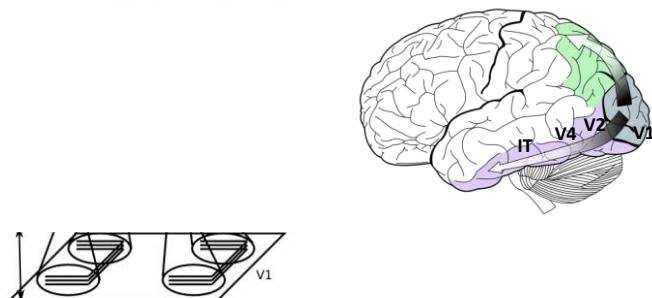
## Selectivity to perceptual variations



- More complex percepts invariant to greater spatial transformations

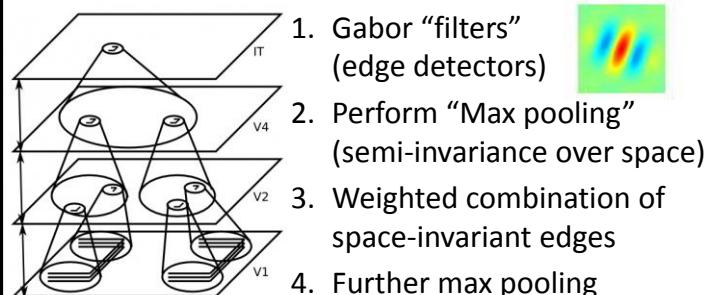
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## HMAX – model of hierarchical vision



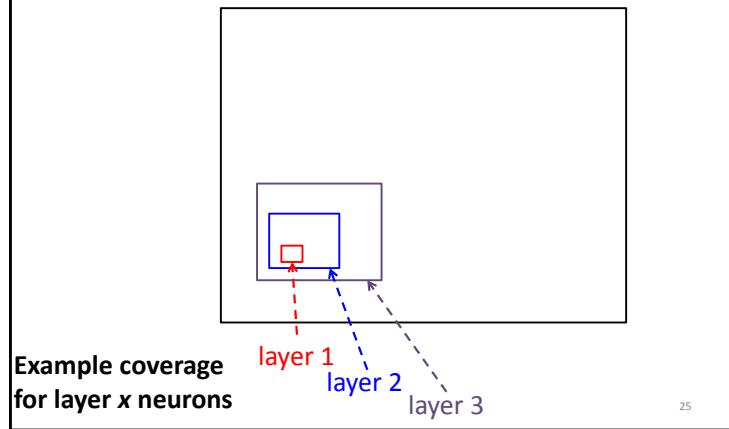
- Higher cortical levels cover larger visual spans
- Object recognition invariant to changes in location and orientation

## HMAX – model of hierarchical vision



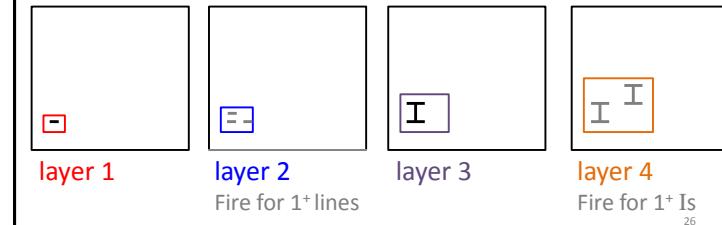
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## Higher HMAX layers cover more space



## Functions of HMAX layers

- Odd layers (layer 1, 3, 5, ...) look for specific combinations of lower-level features
- Even layers (layer 2, 4, 6, ...) provide invariance to some feature changes (e.g., shift in position)



## Functions of HMAX layers

- Odd layers (layer 1, 3, 5, ...) look for specific combinations of lower-level features

$$h = \sum_j w_j r_j^{in} \quad r^{out} = g^{rad}(h)$$

Radial basis function

$g^{rad}(h)$

$h$

- Even layers (layer 2, 4, 6, ...) provide invariance to some feature changes (e.g., shift in position)

$$r^{out} = \max([r_1^{in} \quad r_2^{in} \quad \dots \quad r_J^{in}])$$

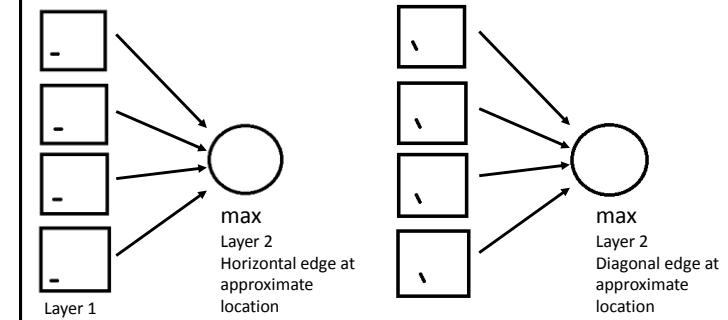
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## Detecting triangles: layer 2

Neuron outputs 1 if desired image viewed, otherwise 0

Layer 1: Specific edge at specific location

Layer 2: Specific edge at slightly varied locations

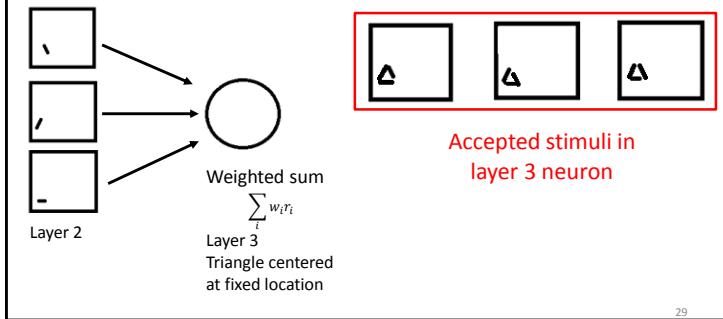


## Detecting triangles: layer 3

Neuron outputs 1 if desired image viewed, otherwise 0

Layer 2: Specific edge at slightly varied locations

Layer 3: Combination of edges



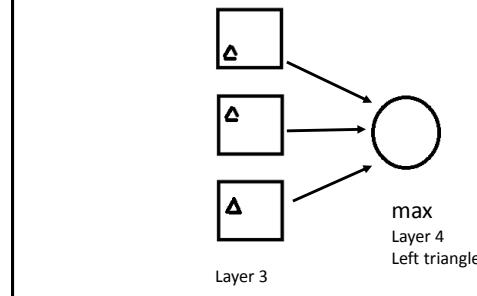
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## Detecting triangles: layer 4

Neuron outputs 1 if desired image viewed, otherwise 0

Layer 3: Combination of edges

Layer 4: Triangle on the left



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