

CISC 3250

Systems Neuroscience

Perception



Professor Daniel Leeds
dleeds@fordham.edu
JMH 332

Pathways to perception in 3 (or fewer) synaptic steps

0 Input through sensory organ/tissue

1 Synapse onto neurons in spinal cord/brain stem

2 Synapse onto neurons in thalamus

3 Synapse onto cortical neurons in “primary ____ cortex”

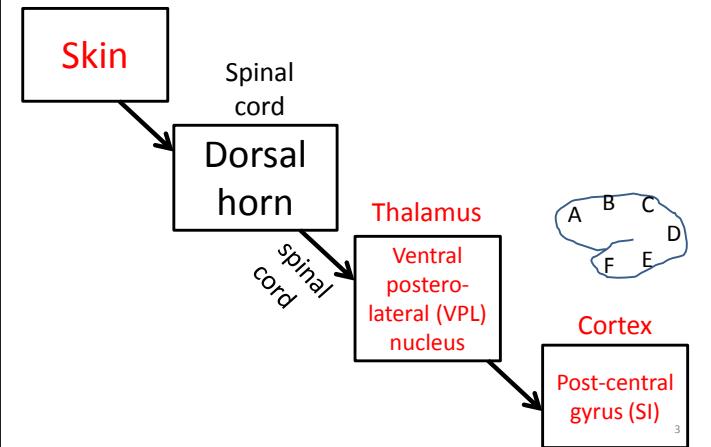
4⁺ Further cortical processing

- Types of percepts in this lecture:
- Tactile (touch)
 - Audition (sound)
 - Vision (sight)



2

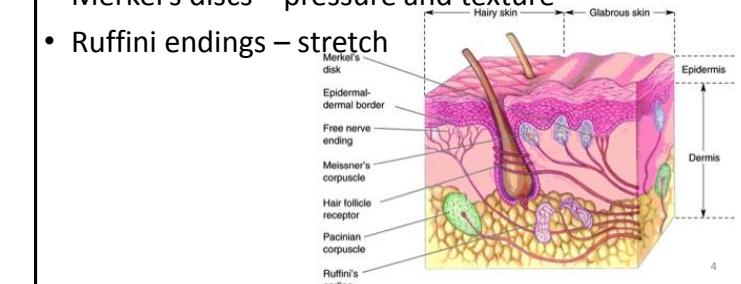
Touch/“Tactile”



Touch: Inputs

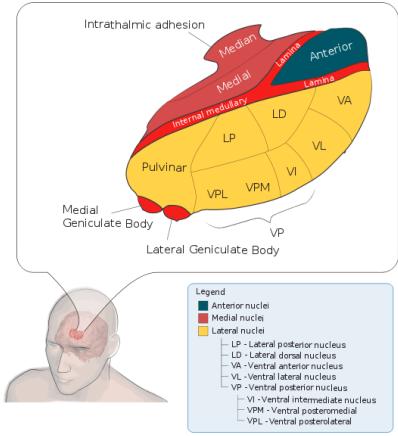
Mechanoreceptors in skin

- Pacinian corpuscles – vibrations
- Meissner's corpuscles – light touch
- Merkel's discs – pressure and texture
- Ruffini endings – stretch



4

Thalamus – the “relay” station



Region names largely based on location

VPL for somatosensation

VPL =
Ventral (bottom)
Posterior (back)
Lateral (side) Nucleus

6

Hearing/“Auditory”

Cochlea

Cochlear nerve

Cochlear nucleus (-> Superior olive) -> Inferior colliculus

Brain stem

Recall: in cochlea have tonotopy
Neurons selective for specific frequencies

Geniculate nuclei at most posterior ventral spots in thalamus

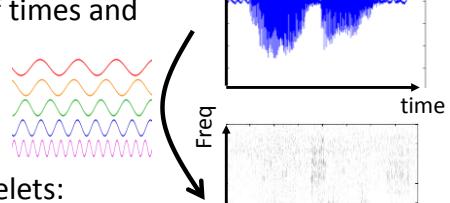
Thalamus

Medial geniculate nucleus (MGN)

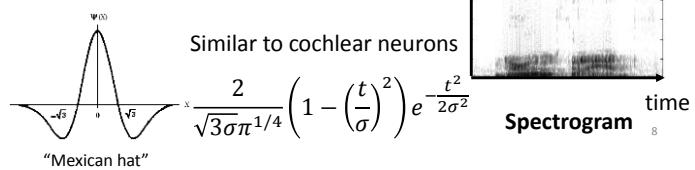
Cortex
Primary auditory cortex (AI)

Hearing and frequency decomposition

Sound consists of times and frequencies

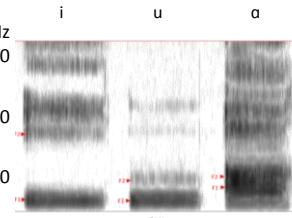


Time-bound wavelets:

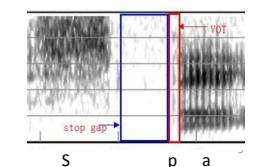


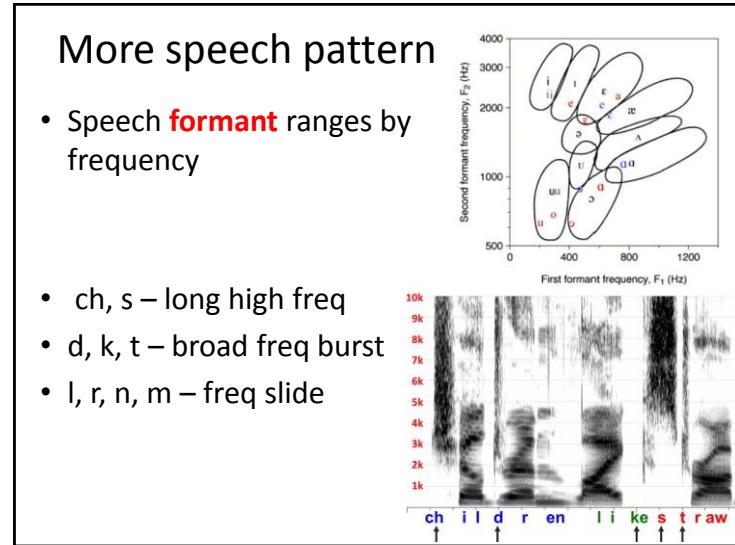
Common patterns in speech

- Vowels (a,e,i,o,u) correspond to steady frequency combinations

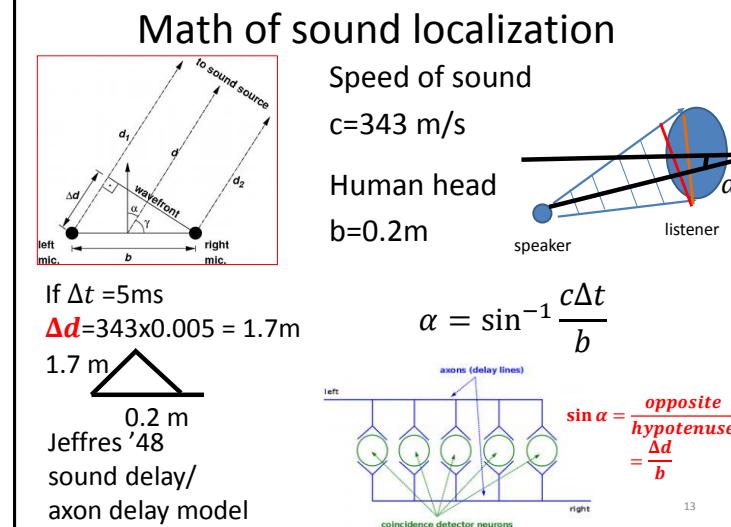
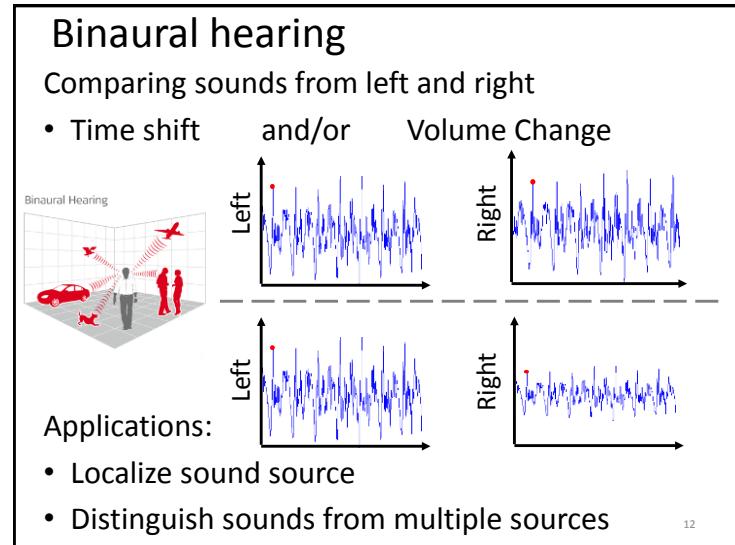
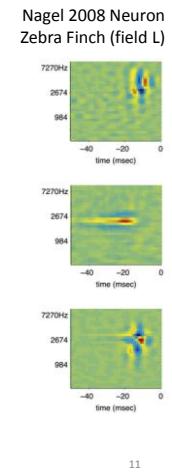


- Consonants may be broad-range frequencies, or sweeps





Spectro-temporal receptive fields



Math of sound localization

Speed of sound
c=343 m/s

Human head
b=0.2m

If $\Delta t = 0.5\text{ms}$
 $\Delta d = 343 \times 0.0005 = 0.17\text{m}$

$$\alpha = \sin^{-1} \frac{c\Delta t}{b}$$

$$\sin \alpha = \frac{0.17}{0.2} = 0.85$$

$$90^\circ = 1.57 \text{ rad } (\frac{\pi}{2} \text{ rad})$$

$$\alpha = \sin^{-1} 0.85 \times \text{radians:}$$

$$\alpha = 58^\circ$$

$$\frac{90x}{1.57} \approx \frac{360x}{2\pi} \text{ degrees}$$

Sound gets R ear @ 1345.2 ms
to L ear @ 1345.7 ms

Math of sound localization

Speed of sound
c=343 m/s

Human head
b=0.2m

$$\alpha = \sin^{-1} \frac{c\Delta t}{b}$$

Pick direction for comparison

$$\Delta t = \begin{cases} > 0 & \text{rightSound earlier} \\ < 0 & \text{leftSound earlier} \end{cases}$$

Math of sound localization

Speed of sound
c=343 m/s

Human head
b=0.2m

$$\alpha = \sin^{-1} \frac{c\Delta t}{b}$$

x radians:
 $\frac{90x}{1.57} \approx \frac{360x}{2\pi} \text{ degrees}$

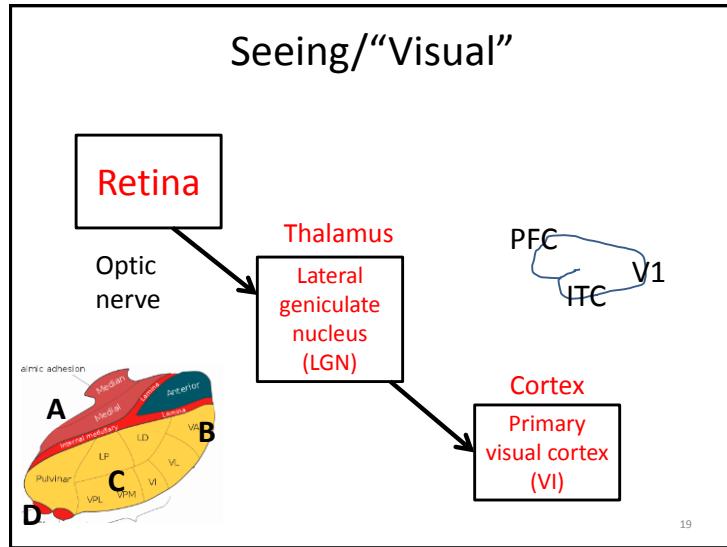
Sound gets R ear @ 258.5 ms 285.5ms
Get to L ear @ 285.3 ms

Which ear is sound closest to?
The ear that sound arrives at first
Ear with smaller time of arrival

$$\Delta d = c\Delta t = 343 \times (0.2855 - 0.2853)$$

$$\sin \alpha = \frac{\Delta d}{b} = \frac{343 \times 0.0002}{0.2} = \frac{.0686}{0.2} = 0.35$$

What's my α ?
Closer to L ear

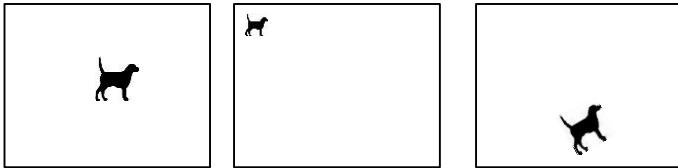
$$\alpha = \text{asin}(0.35) = 20^\circ$$


Sensitivity to perceptual variations

- V1: Surround-suppression for shifted edges

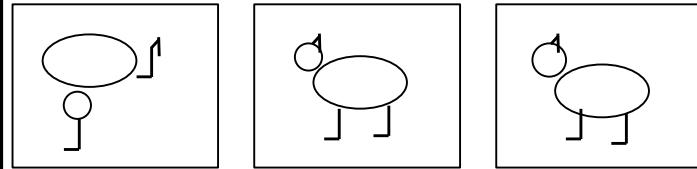


- ITC/PFC: Same object detected at diverse locations and scales



21

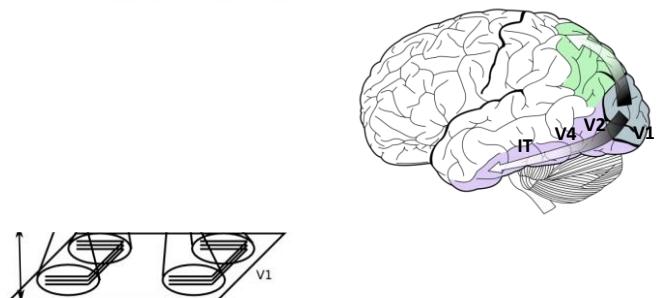
Selectivity to perceptual variations



- More complex percepts invariant to greater spatial transformations
 - But if transformation are TOO large, invariance breaks down

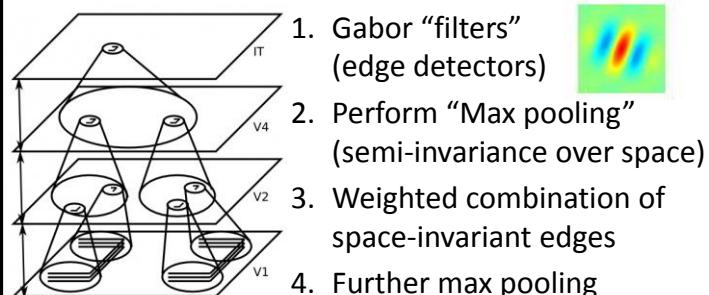
22

HMAX – model of hierarchical vision



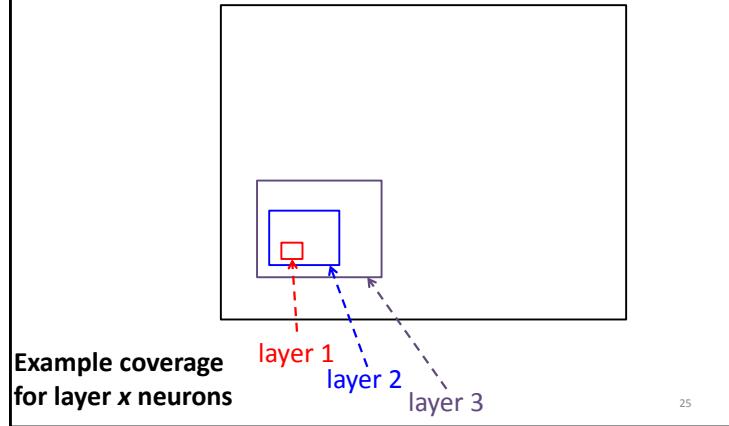
- Higher cortical levels cover larger visual spans
- Object recognition invariant to changes in location and orientation

HMAX – model of hierarchical vision



24

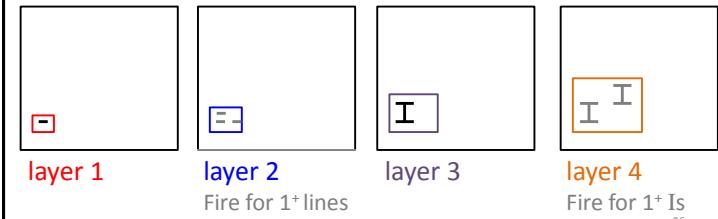
Higher HMAX layers cover more space



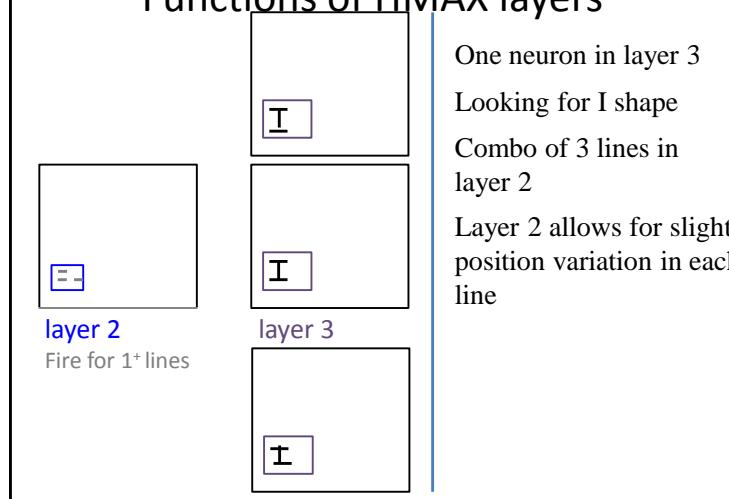
Functions of HMAX layers

- Odd layers (layer 1, 3, 5, ...) look for specific combinations of lower-level features
- Even layers (layer 2, 4, 6, ...) provide invariance to some feature changes (e.g., shift in position)

Neuron in layer L combines info from neurons in layer L-1



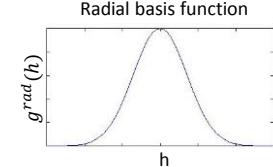
Functions of HMAX layers



Functions of HMAX layers

- Odd layers (layer 1, 3, 5, ...) look for specific combinations of lower-level features

$$h = \sum_j w_j r_j^{in} \quad r^{out} = g^{rad}(h)$$



- Even layers (layer 2, 4, 6, ...) provide invariance to some feature changes (e.g., shift in position)

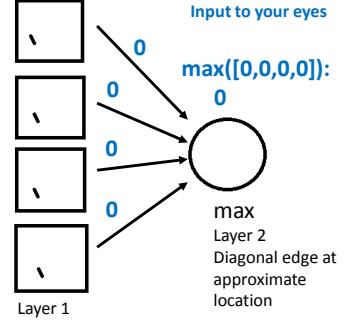
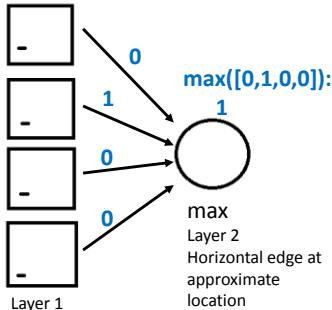
$$r^{out} = \max([r_1^{in} \quad r_2^{in} \quad \dots \quad r_J^{in}])$$

Detecting triangles: layer 2

Neuron outputs 1 if desired image viewed, otherwise 0

Layer 1: Specific edge at specific location

Layer 2: Specific edge at slightly varied locations



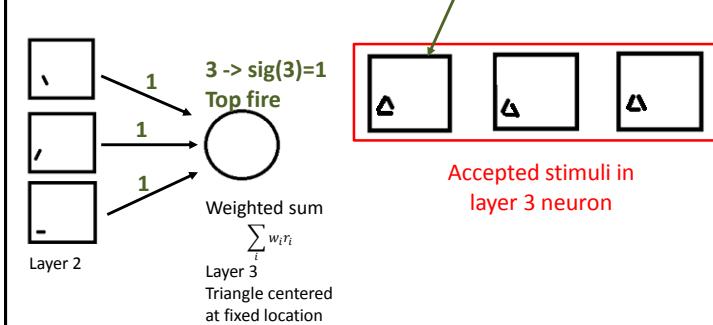
29

Detecting triangles: layer 3

Neuron outputs 1 if desired image viewed, otherwise 0

Layer 2: Specific edge at slightly varied locations

Layer 3: Combination of edges



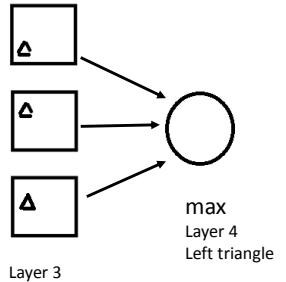
30

Detecting triangles: layer 4

Neuron outputs 1 if desired image viewed, otherwise 0

Layer 3: Combination of edges

Layer 4: Triangle on the left



31

How do CNNs work? Convolutional Neural Networks

Collection of "neurons" divided among k layers

Each neuron looks for one pattern



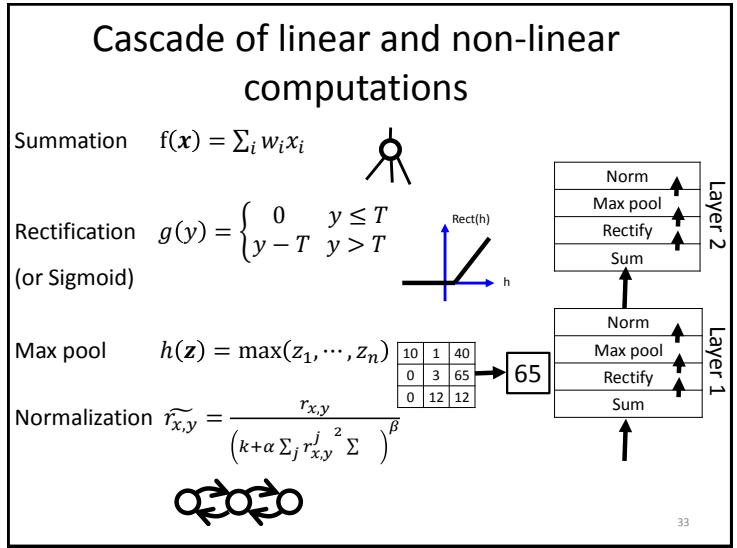
Each neuron looks for same pattern at multiple locations in input



10	1	40	0
0	3	65	15
0	12	12	0
0	5	15	0

0	0	10	25
0	90	0	6
0	40	25	0
0	14	0	0

32



Layer 1

Layer 2