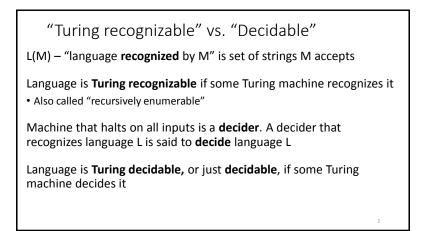
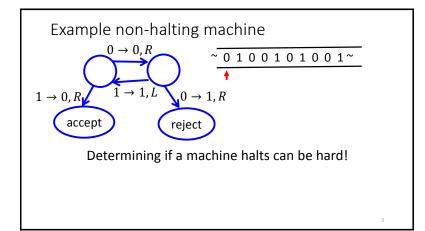
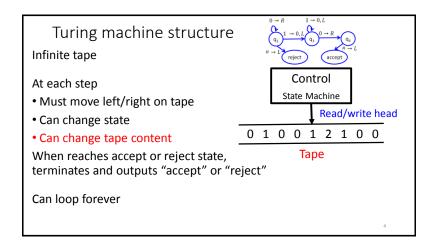
### CISC 4090 Theory of Computation

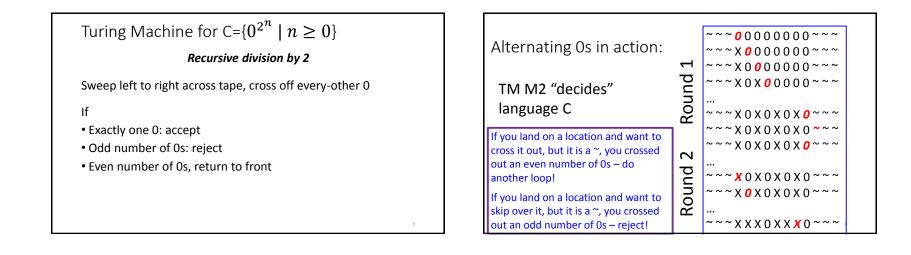
Turing Machines, continued: Transducers, MultiTape, NonDeterminism

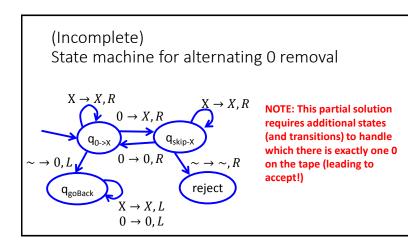
> Professor Daniel Leeds dleeds@fordham.edu JMH 332







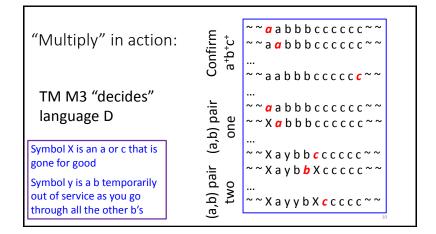




Language D={a<sup>i</sup>b<sup>j</sup>c<sup>k</sup> | k=ixj and i,j,k>0} Multiplication on a Turing Machine! Consider 2x3=6

# TM M3 to decide $D=\{a^ib^jc^k | k=ixj and i, j, k>0\}$

Scan string to confirm form is a<sup>+</sup>b<sup>+</sup>c<sup>+</sup> • if so: go back to front; if not: reject X out first a, for each b, x off that b and x off one c • If run out of c's but b's left: reject Restore crossed out b's, repeat b—c loop for next a • If all a's gone, check if any c's left • If c's left: reject; if no c's left: accept



Transducers: generating language

So far our machines accept/reject input

Transduction: Computers transform from input to output • New TM: given *i* a's and *j* b's on tape, print out *ixj* c's Transducer: Write  $c^k$ , k=ixj, given i a's, j b's,

Scan string to confirm form is a<sup>+</sup>b<sup>+</sup>

• if so: go back to front; if not: reject

X out first a, for each b, Y off that b and add c to the end  $% \left( {{\mathbf{x}}_{i}}\right) =\left( {{\mathbf{x}}_{i}}\right) \left( {{\mathbf{x}}_{i}}\right)$ 

Restore crossed out b's, repeat b—c loop for next a • If all a's gone, accept

# TM 4: Element distinctivenessTM 4 solutionGiven a list of strings over {0,1}, separated by #, accept if all<br/>strings are different:1. Place mark on top of left-most symbol. If it is blank: accept;<br/>if it is #: continue, otherwise: rejectExample: 01101#1011#000102. Scan right to next # and place mark on it. If none<br/>encountered and reach blank: accept3. Zig-zag to compare strings to right of each marked #<br/>4. Move right-most marked # to the right. If no more #: move<br/>left-most # to its right and the right-most # to the right of the<br/>new first marked #. If no # available for second marked #:<br/>accepts5. Go to step 3s

### Decidability

How do we know decidable?

- Simplify problem at each step toward goal
- Can prove formally number of remaining symbols at each step

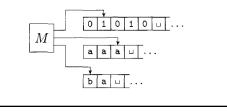
Showing language is Turing recognizable but not decidable is harder

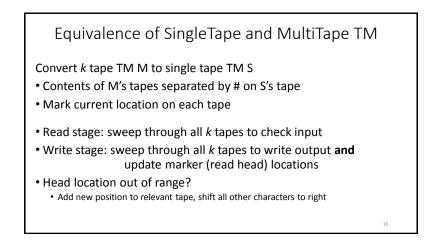
- Many equivalent variants of TM
- TM that can "stay put" on tape for a given transition
- TM with multiple tapes
- TM with non-deterministic transitions

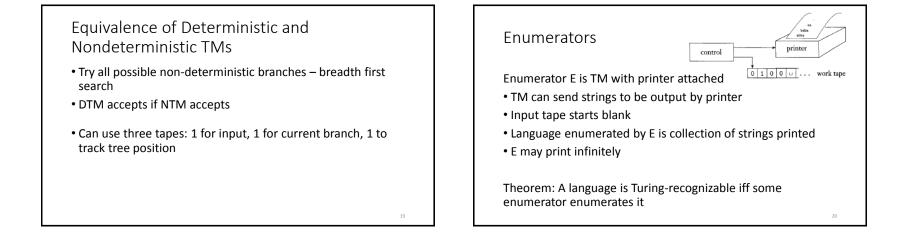
Can select convenient alternative for current problem

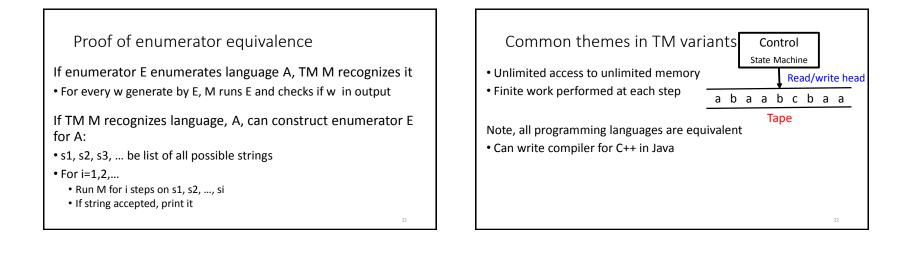
# MultiTape TM

- Each tape has own ReadWrite Head
- Initially tape 1 has input string, all other tapes blank
- Transition does read/write on all heads at once









# An Algorithm

is a collection of simple instructions for carrying out some task

# Hilbert's Problems

In 1900, David Hilbert proposed 23 mathematical problems

### Problem #10

- Devise algorithm to determine if a polynomial has an integral root.
- Example:  $6x^3yz^2+3xy^2-x^3-10$  has root x=5, y=3, z=0 General algorithm for Problem 10 does not exist!

## Church-Turing Thesis

- Intuition of thesis: algorithm == corresponding Turing machine
- Algorithm described by TM also can be describe by  $\lambda-\mbox{calculus}$  (devised by Alonzo Church)

### Hilbert's 10<sup>th</sup> problem

Is language D decidable, where  $D=\{p \mid p \text{ is polynomial with integral root}\}$ 

Devise procedure:

- Try all ints, starting at 0: x=0, 1, -1, 2, -2, 3, -3, ...
- You may never terminate so not decidable

Exception: univariate case for root is decidable

### Levels of description

### For FA and PDA

• Formal or informal description of machine operation

### For TM

- Formal or informal description of machine operation
- OR just describe algorithm
  - Assume TM confirms input follows proper tape string format

### Graph connectivity problem

Let A be all strings representing graphs that are connected (any node can be reached by any other)

- A={<G> | G is connected undirected graph}
- Describe TM M to decide language

### Algorithm:

- 1. Select and mark first node of G
- 2. Repeat below until no new nodes marked:
  - For each node in G, mark if it is attached to already-marked node
- 3. Scan all nodes of G if all marked, accept; else, reject