

# Dimensionality reduction

CISC 5800  
Professor Daniel Leeds

## Opening note on dimensional differences

Each dimension corresponds to a feature/measurement

Magnitude differences for each measurement (e.g., animals):

- $x_1$  – speed (mph) 0-100
- $x_2$  – weight (pounds) 10-1000
- $x_3$  – size (feet) 2-20



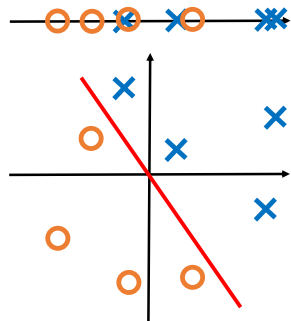
Problem for learning:

$$w_j \leftarrow w_j + \varepsilon x_j^i (y^i - g(w^T x^i)) - \frac{w_j}{\lambda}$$

**Normalize:**  $r_1 = \frac{x_1 - \mu_1}{\sigma_1}$  or  $r_1 = \frac{x_1 - \min_1}{\max_1 - \min_1}$

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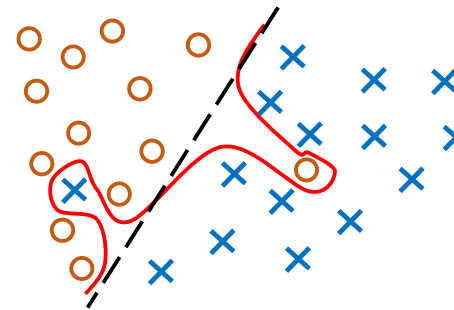
## The benefits of extra dimensions



- Finds existing complex separations between classes

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## The risks of too-many dimensions

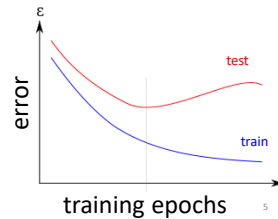


- High dimensions with kernels over-fit the outlier data
- Two dimensions ignore the outlier data

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## Training vs. testing

- **Training**: learn parameters from set of data in each class
- **Testing**: measure how often classifier correctly identifies new data
- More training reduces classifier error  $\epsilon$ 
  - More gradient ascent steps
  - More learned feature
- Too much training causes worse testing error – overfitting



## Goal: High Performance, Few Parameters

- “Information criterion”: performance/parameter trade-off
- Variables to consider:
  - $L$  likelihood of train data after learning
  - $k$  number of parameters (e.g., number of features)
  - $m$  number of points of training data
- Popular information criteria:
  - Akaike information criterion **AIC**:  $\ln(L) - k$
  - Bayesian information criterion **BIC**:  $\ln(L) - 0.5 k \ln(m)$

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## Decreasing parameters

- Force parameter values to 0
  - L1 regularization
  - Support Vector selection
  - Feature selection/removal
- Consolidate feature space
  - Component analysis

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## Feature removal

- Start with feature set:  $F = \{x_1, \dots, x_k\}$
  - Find classifier performance with set  $F$ :  $\text{perform}(F)$
  - Loop
    - Find classifier performance for removing feature  $x_1, x_2, \dots, x_k$ :  
 $\text{argmax}_i \text{perform}(F - x_i)$
    - Remove feature that causes least decrease in performance:  
 $F = F - x_i$
- AIC**:  $\ln(L) - k$   
**BIC**:  $\ln(L) - 0.5 k \ln(m)$
- Repeat, using AIC or BIC as termination criterion

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AIC testing:  $\ln(L)-k$ 

Features	k (num features)	L (likelihood)	AIC
F	40	0.1	-42.3
F- $\{x_3\}$	39	0.04	-42.2
F- $\{x_3, x_{74}\}$	38	0.02	-41.9
F- $\{x_3, x_{24}, x_{32}\}$	37	0.01	-41.6
F- $\{x_3, x_{24}, x_{32}, x_{15}\}$	36	0.003	-41.8

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## Feature selection

**AIC:**  $\ln(L) - k$ **BIC:**  $\ln(L) - 0.5 k \ln(m)$ 

- Find classifier performance for just set of 1 feature:  $\text{argmax}_i \text{perform}(\{x_i\})$
- Add feature with highest performance:  $F=\{x_i\}$
- Loop
  - Find classifier performance for adding one new feature:  $\text{argmax}_i \text{perform}(F+\{x_i\})$
  - Add to F feature with highest performance increase:  $F=F+\{x_i\}$

Repeat, using AIC or BIC as termination criterion

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## Capturing links between features

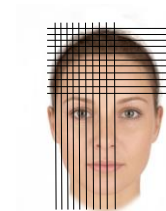
Document1 Document2 Document3

Wolf	12	4	1
Lion	16	3	2
Monkey	5	11	4
Sky	7	3	14
Tree	2	8	5
Cloud	6	2	12
⋮	⋮	⋮	⋮

With large number of features,  
some features  $x_j$  and  $x_k$  act similarly $x_{\text{wolf}}$  &  $x_{\text{lion}} \rightarrow u_{\text{predator}}$  $x_{\text{sky}}$  &  $x_{\text{cloud}} \rightarrow u_{\text{atmosphere}}$ Approximate  $x^1 = \begin{bmatrix} x_1^1 \\ \vdots \\ x_N^1 \end{bmatrix}$ with  $u^1 = \begin{bmatrix} u_1^1 \\ \vdots \\ u_{N'}^1 \end{bmatrix}$ **Automatically learn summary features**

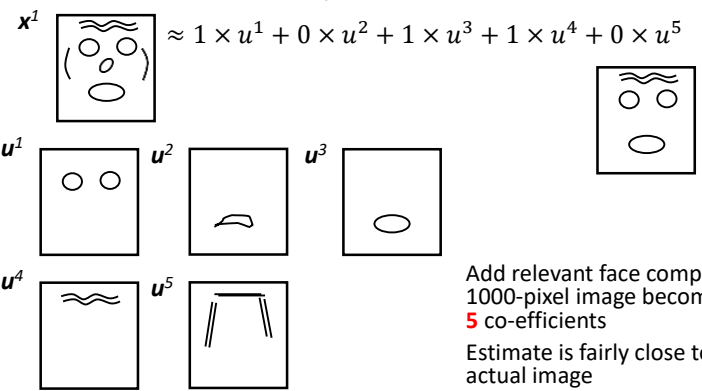
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## Image features

Image as grid of  $n \times m$  pixelsFind representative component  
features as pixel patterns

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Cartoon face example:

$$\mathbf{x}^1 \approx 1 \times \mathbf{u}^1 + 0 \times \mathbf{u}^2 + 1 \times \mathbf{u}^3 + 1 \times \mathbf{u}^4 + 0 \times \mathbf{u}^5$$


Add relevant face components  
1000-pixel image becomes  
**5** co-efficients  
Estimate is fairly close to  
actual image

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## Component analysis

Each data point  $\mathbf{x}^i$  in D can be reconstructed as sum of components  $\mathbf{u}$ :

- $\mathbf{x}^i = \sum_{q=1}^T z_q^i \mathbf{u}^q$
- $z_q^i$  is weight on  $q^{\text{th}}$  component to reconstruct data point  $\mathbf{x}^i$

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## Evaluating components

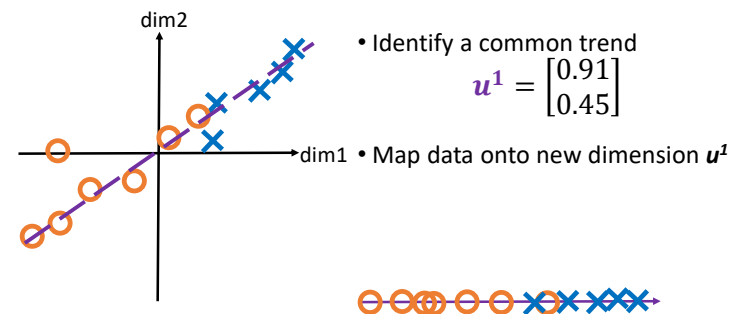
Components learned in order of descriptive power

Compute reconstruction error for all data by using first  $r$  components:

$$\text{error} = \sum_i \left( \sum_j \left( \mathbf{x}_j^i - \sum_{q=1}^r z_q^i \mathbf{u}_j^q \right)^2 \right)$$

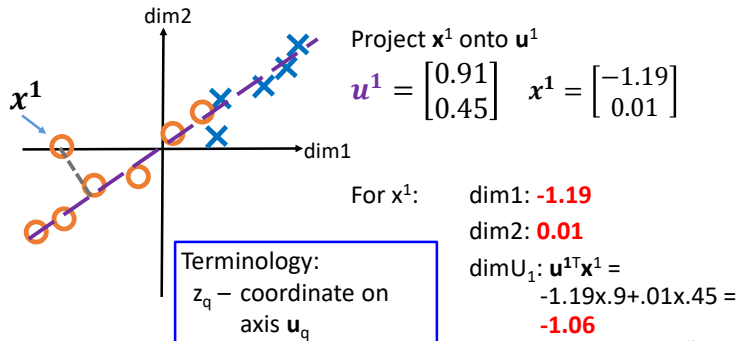
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## Defining new feature axes



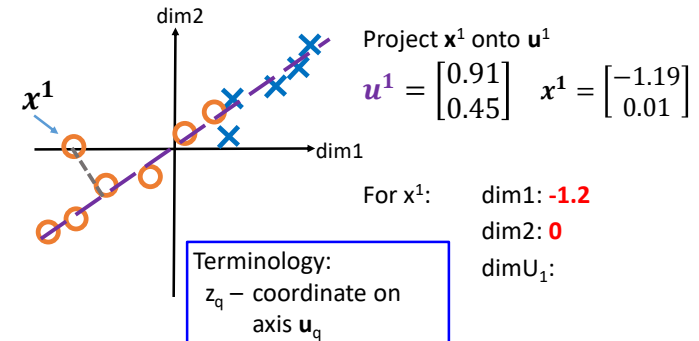
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## Defining new feature axes



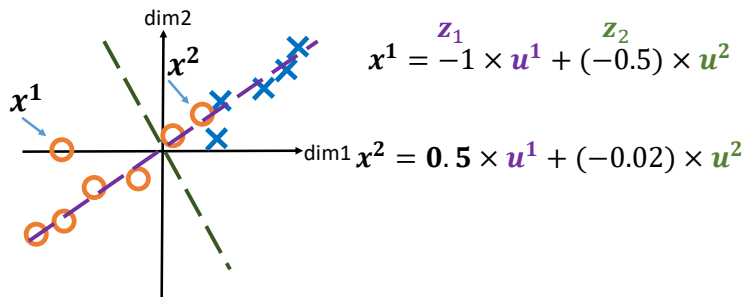
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## Defining new feature axes



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## Defining data points with new axes



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## Component analysis

Each data point  $\mathbf{x}^i$  in  $D$  can be reconstructed as sum of components  $\mathbf{u}$ :

- $\mathbf{x}^i = \sum_{q=1}^T z_q^i \mathbf{u}^q$
- $z_q^i$  is weight on  $q^{\text{th}}$  component to reconstruct data point  $\mathbf{x}^i$

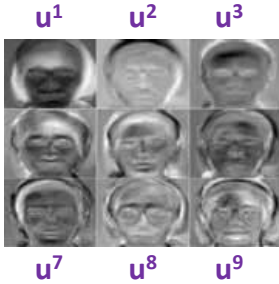
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## Component analysis: examples

$$\mathbf{x}^i = \sum_{q=1}^T z_q^i \mathbf{u}^q$$

“Eigenfaces” – learned from set of face images

$\mathbf{u}$ : nine components



$\mathbf{x}^4$ : data reconstructed



$$z_1 \mathbf{u}^1 + \dots + z_9 \mathbf{u}^9 \approx$$

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## Types of component analysis

Capture links between features as “components”

- Principal component analysis (PCA)
- Independent component analysis (ICA)
- Non-negative matrix factorization (NMF)

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## Principal component analysis (PCA)

Describe every  $\mathbf{x}^i$  with small set of components  $\mathbf{u}^{1:Q}$

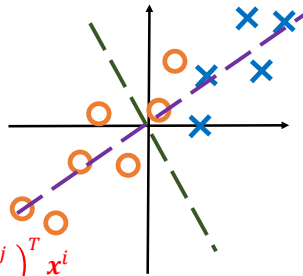
Use same  $\mathbf{u}^1, \dots, \mathbf{u}^T$  for all  $\mathbf{x}^i$

All components orthogonal:

$$(\mathbf{u}^i)^T \mathbf{u}^j = 0 \quad \forall i \neq j$$

$$\mathbf{x}^i = \sum_{q=1}^Q z_q^i \mathbf{u}^q$$

NOTE: In PCA  $z_j^i = (\mathbf{u}^j)^T \mathbf{x}^i$



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## Independent component analysis (ICA)

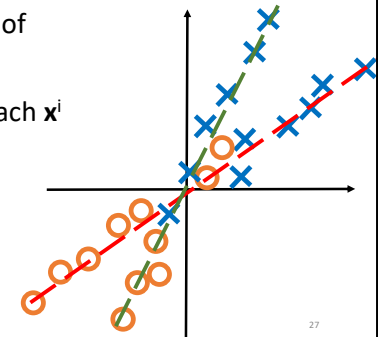
Describe every  $\mathbf{x}^i$  with small set of components  $\mathbf{u}^{1:Q}$

Can use **different**  $\mathbf{u}^1, \dots, \mathbf{u}^Q$  for each  $\mathbf{x}^i$

No orthogonality constraint:

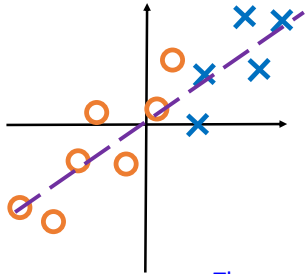
$$(\mathbf{u}^i)^T \mathbf{u}^j \neq 0 \quad \forall i \neq j$$

$$\mathbf{x}^i = \sum_{q=1}^Q z_q^i \mathbf{u}^q$$



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## Idea of learning in PCA



1.  $D = \{\mathbf{x}^1, \dots, \mathbf{x}^n\}$ , data 0-center
2. Component index:  $q=1$
3. Loop
  - Find direction of highest variance:  $\mathbf{u}^q$ 
    - Ensure  $|\mathbf{u}^q| = 1$
  - Remove  $\mathbf{u}^q$  from data:
 
$$D = \{\mathbf{x}^1 - z_q^1 \mathbf{u}^q, \dots, \mathbf{x}^n - z_q^n \mathbf{u}^q\}$$

$$(\mathbf{u}_i)^T \mathbf{u}_j = 0 \quad \forall i \neq j$$

Thus, we guarantee  $z_j^i = \mathbf{u}_j^T \mathbf{x}^i$

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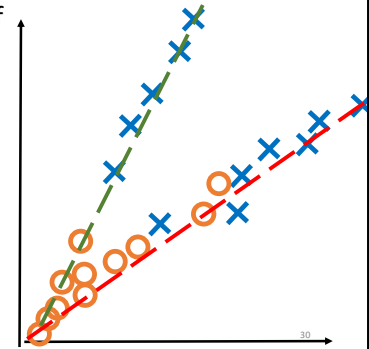
## Non-negative matrix factorization (NMF)

Describe every  $\mathbf{x}^i$  with small set of components  $\mathbf{u}^{1:T}$

All components and weights non-negative

$$\mathbf{u}^i \geq 0, z_q^i \geq 0 \quad \forall i, q$$

$$\mathbf{x}^i = \sum_{q=1}^Q z_q^i \mathbf{u}^q$$



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## Types of component analysis

Principal component analysis (PCA):

- Minimal components to describe all data
- All components orthogonal:  $(\mathbf{u}_i)^T \mathbf{u}_j = 0 \quad \forall i \neq j$

Independent component analysis (ICA):

- Minimize components to describe each data point  $\mathbf{x}^i$
- Can focus on different components for different  $\mathbf{x}^i$

Non-negative matrix factorization (NMF):

- All data  $\mathbf{x}^i$  non-negative
- All components and weights non-negative  $\mathbf{u}_j \geq 0, z_q^i \geq 0 \quad \forall i, q$

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$$\mathbf{x}^i = \sum_{q=1}^Q z_q^i \mathbf{u}_q$$